

Cuk converter

Thursday, March 11, 2021 9:17 AM

Motivation

- Synthesize a DC-DC circuit that can increase / dec. g/p voltage.
- Both g/p & o/p currents non-pulsating or continuous.

Buck | Boost | Buck-boost

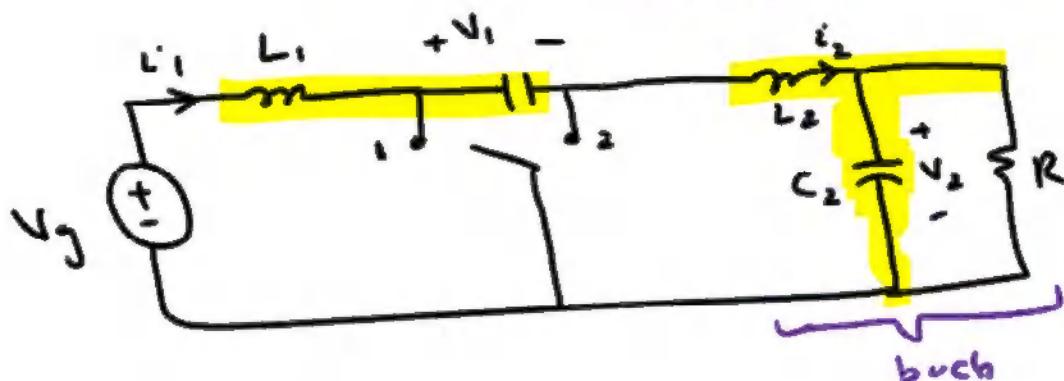
Gain of buck-boost = gain of buck \times gain of boost

$$\frac{D}{D'} = \underbrace{(\text{D})}_{\text{concurrent design}} \left(\frac{1}{D'} \right)$$

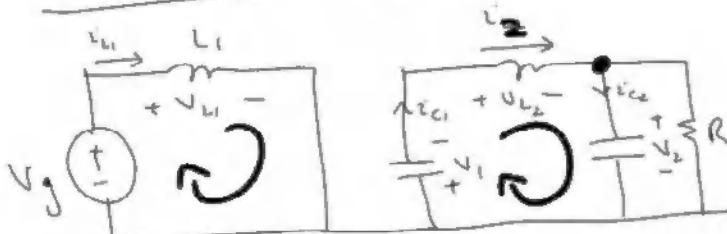
CUK converter

↳ g/p stage = Boost

↳ o/p , = Buck



At position #1



$$V_{L1} = V_g \quad \text{KVL}$$

$$V_{L2} = -V_1 - V_2 \quad \text{KVL}$$

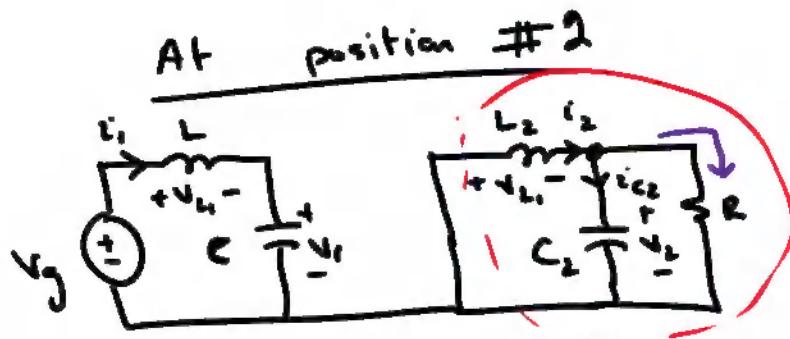
$$i_{C1} = i_2 \quad \text{KCL}$$

$$\rightarrow i_{C2} = i_2 - \frac{V_2}{R} \quad \text{KCL}$$

small ripple approximation

$$V_{L1} = V_g$$

$$\boxed{V_{L2} = -V_1 - V_2}$$



$$V_{L2} = -V_1 - V_2$$

$$i_{C1} = I_2$$

$$i_{C2} = I_2 - \frac{V_L}{R}$$

$$V_{L1} = V_g - V_1 \quad \left. \begin{array}{l} \\ \end{array} \right\} KVL$$

$$V_{L2} = -V_2 \quad \left. \begin{array}{l} \\ \end{array} \right\} KCL$$

$$i_{C1} = I_1$$

$$i_{C2} = I_2 - \frac{V_L}{R} \quad \left. \begin{array}{l} \\ \end{array} \right\} KCL$$

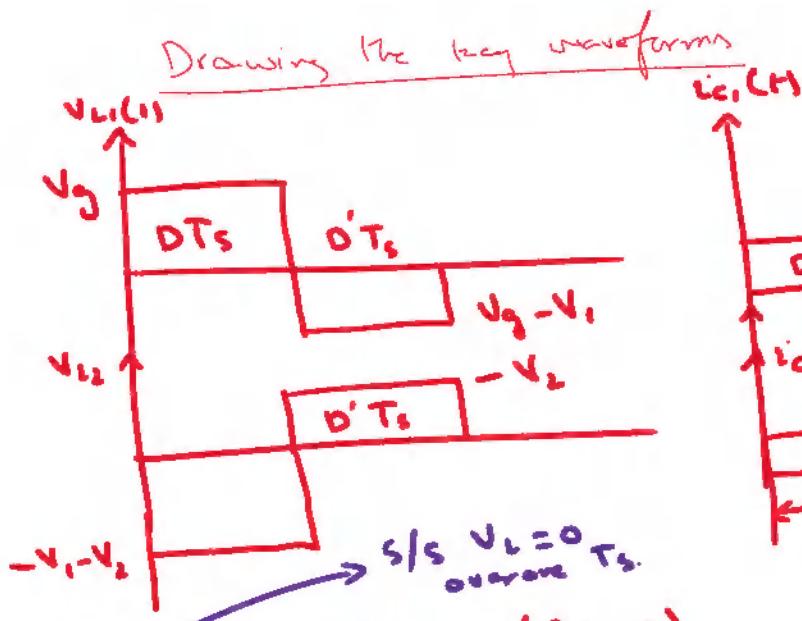
Small ripple approximation:

$$V_{L1} = V_g - V_1$$

$$V_{L2} = -V_2$$

$$i_{C1} = I_1$$

$$i_{C2} = I_2 - \frac{V_L}{R}$$



$$\langle V_{L1} \rangle = 0 = V_g D + D' (V_g - V_1)$$

$$= V_g |D'|$$

$$\langle V_{L2} \rangle = 0 = D (-V_1 - V_2) + D' (-V_2)$$

$$V_2 = \frac{-D}{D'} V_g - \textcircled{A}$$

$$\langle i_{C1} \rangle = 0 = D I_2 + D' I_1$$

$$I_1 = \left(-\frac{D}{D'} \right) I_2 = -\frac{D}{D'} \frac{V_L}{R}$$

$$= \left(\frac{D}{D'} \right)^2 \frac{V_L}{R}$$

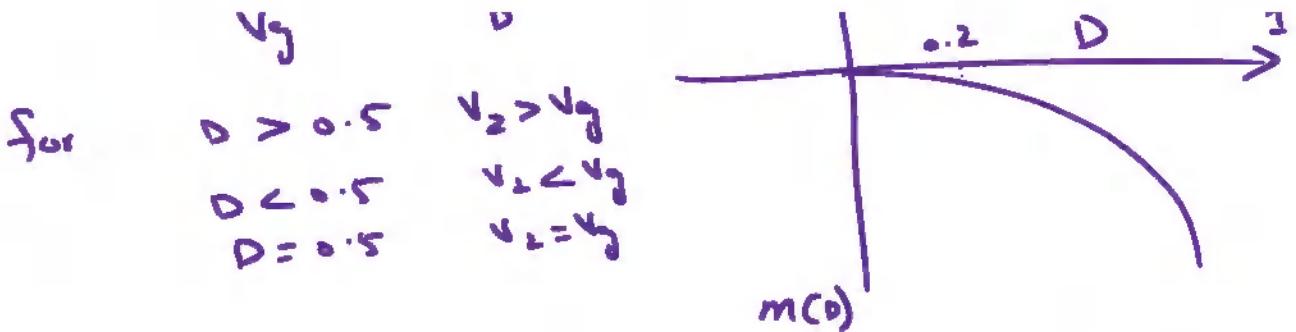
$$\langle i_{C2} \rangle = I_2 - \frac{V_L}{R} = 0$$

$$I_2 = -\frac{D}{D'} \frac{V_g}{R}$$

$$M(D) = \frac{V_2}{V_g} = \frac{-D}{D'} = \frac{-D}{1-D}$$

$$= \frac{D}{D+1}$$





L_1 Expression based on

$$= \frac{v_g}{g \Delta i_1} DT_s$$

L_2 expression

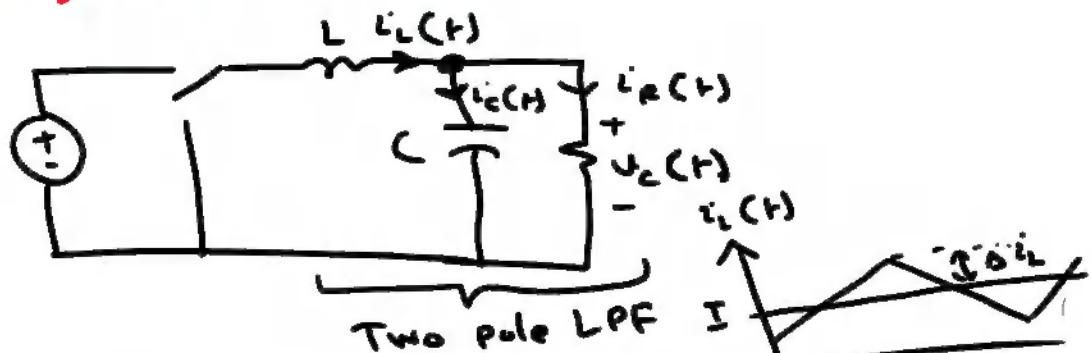
$$L_2 = \frac{v_1 + v_2}{g \Delta i_2} DT_s$$

C_1 expression

$$= \frac{i_2}{g \Delta v_1} DT_s$$

how to determine the C_2 .

→ $i_{c_2}(t)$ is continuous.

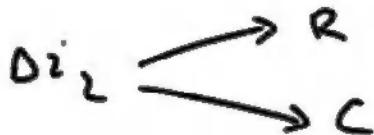


$$i_L(t) = I + \Delta i_2$$

- ... all flow through R_f

$$z_L(t) = + -$$

DC component I can only flow through R
 b/c $x_C = \frac{1}{2\pi f_C} = \infty$ so I can't flow through C .



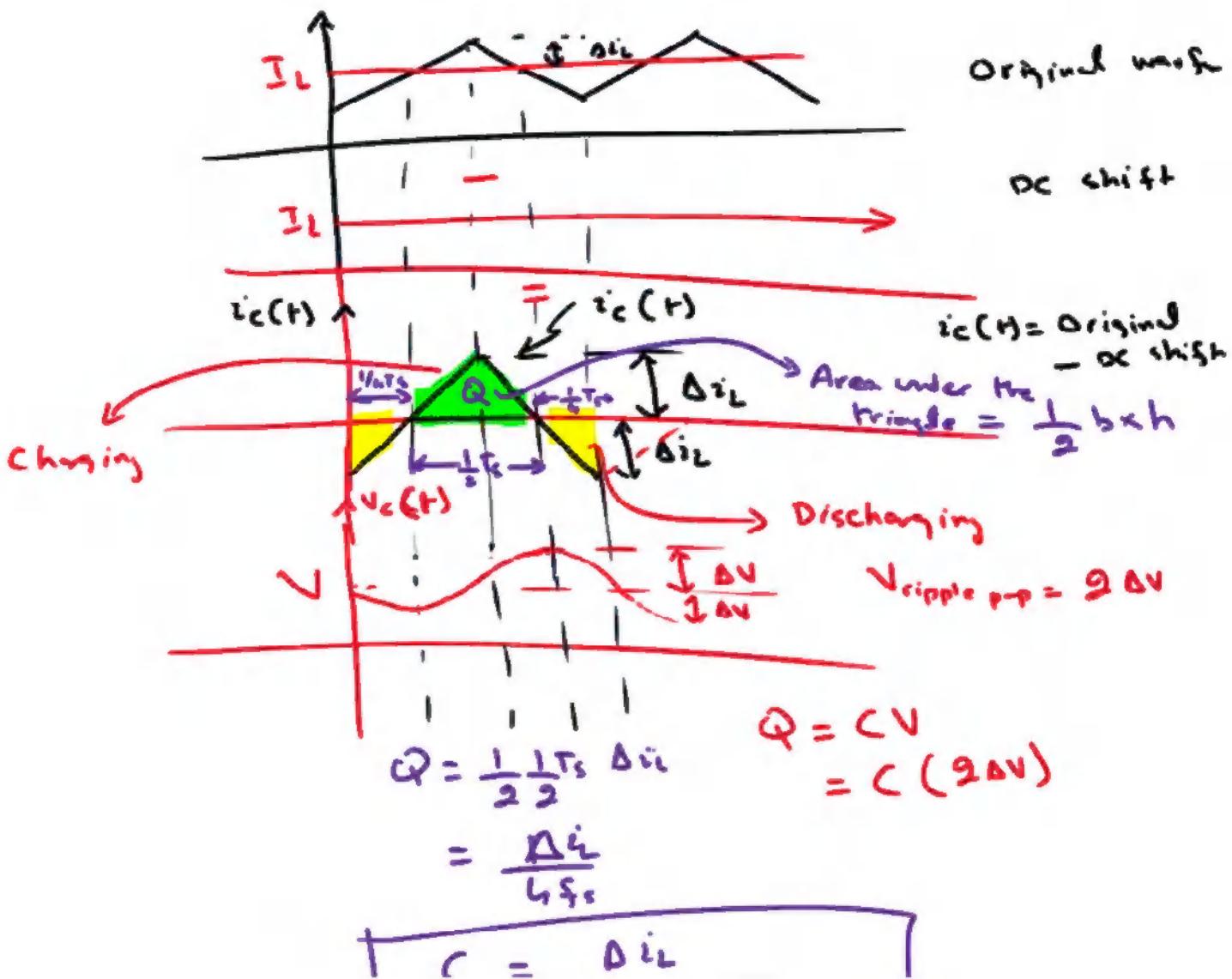
If $z_C > R$
 $z_C < R$

In a well designed converter

$$x_C \ll R$$

To ensure this C is kept large $x_C = \frac{1}{2\pi f_C}$

Ideally all Δi_L flows through 'C'



$$C = \frac{D i_L}{8 f_s \Delta V}$$

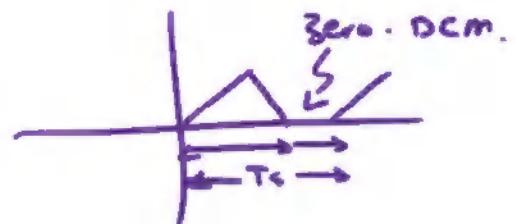
Discussion

i) All DC-DC are non-linear. first order

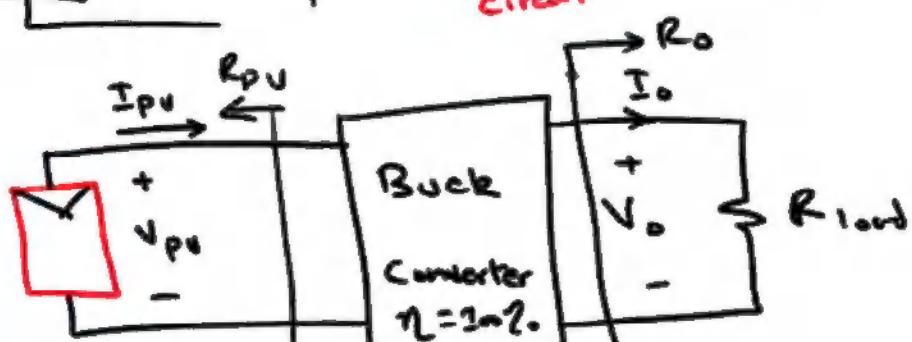
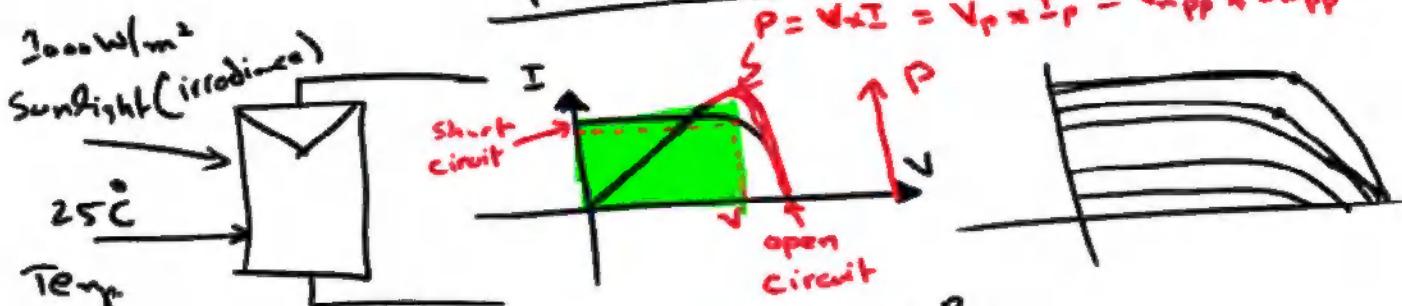
↳ subcircuits are linear [2nd order]

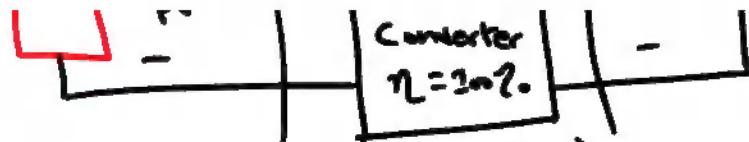
but high freq switching changes
their structure & its periodic structure
changes make the converter itself a
non-linear circuit.

→ In all converters, $i_L > 0$ no time is
called continuous conduction mode (CCM).



Application of basic converter in photovoltaic system.



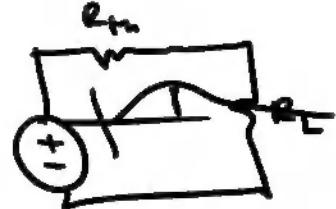
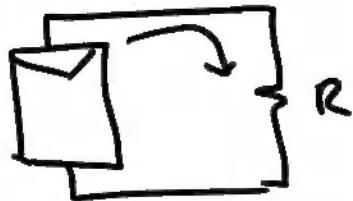
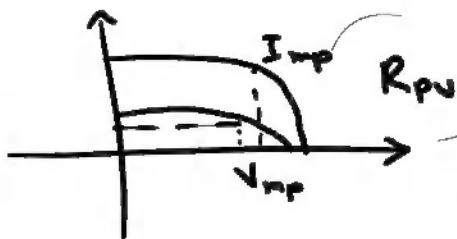


$$V_o = DV_{in}$$

$$V_o = D V_{PV}$$

$$P_{in} = P_o \quad I_o = \frac{\sum I_o}{R_o}$$

$$R_{PV} = \frac{V_{PV}}{I_{PV}} = \frac{V_o / D}{I_o / D} = \frac{V_o}{I_o} \cdot \frac{D}{D^2} = \frac{R_o}{D^2} = \frac{R_{load}}{D^2}$$



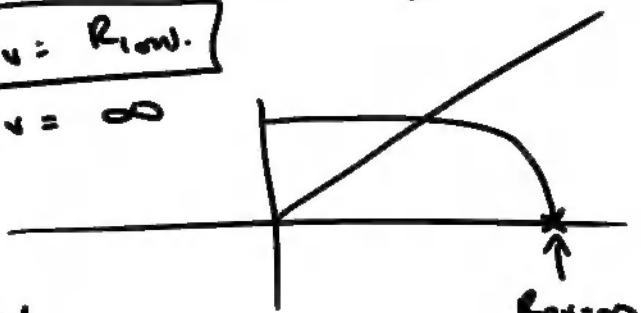
$$R = R_{PV}$$

$$R_{PV} = \frac{R_{load}}{D^2}$$

if $D = 1$
 $D = 0$

$$R_{PV} = R_{load}$$

$$R_{PV} = \infty$$



if $R_{load} > R_{PV}$

buck converter can't match
 the impedance & hence can't
 transfer the MPP or it can't track MPT.